



## A MATHEMATICAL ANALYSIS OF FUEL COMBUSTION RESULTING IN AIR POLLUTANTS

<sup>1</sup>Rekha Dubey, <sup>2</sup>Dr. Jitendra K Sharma, <sup>3</sup>Dr. Sonu Sen

<sup>1</sup>Research Scholar, Shri Rawatpura Sarkar University, Raipur, Chhattisgarh

<sup>2</sup>Associate Professor, Shri Rawatpura Sarkar University, Raipur, Chhattisgarh

<sup>3</sup>Assistant Professor, Shri Neelkantheshwar Govt. P.G. College, Khandwa, M.P.

### Abstract

This paper manages the investigation of barometrical contamination to numerically depict the spatial and worldly dissemination of contaminations transmitted into the environment. The numerical scattering displaying of contaminations from power plants is acted in the product bundle FlexPDE. Subsequently, an assessment of seriousness of air contamination can be accomplished, utilizing the poisons focus and air conditions. The checked poisons are SO<sub>2</sub>, NO<sub>x</sub>, and PM.

**Keywords:** air quality, mathematical modeling, numerical simulation, pollutant dispersion.

### 1. Introduction:

As a general rule, the air dissemination alludes to the conduct of gases and articles in violent stream. In the logical writing, there are two key models for portraying air dissemination. The first is the Eulerian approach, in which the conduct of species is portrayed comparative with a fixed arrange framework. The Eulerian depiction is the normal model of treating heat also, mass exchange marvels. The subsequent model is the Lagrangian approach, in which the focus varieties are portrayed as a component of moving liquid. The two methodologies yield various sorts of numerical connections for the species fixations that can, eventually, be

connected. Every one of the two models of articulation is a legitimate depiction of fierce dissemination [1], [2]. There are distinctive programming bundles that can reenact different change measures happening in presence of contamination and in view of test information. The principle trouble with these projects is their adjustment, with the end goal that the showed results will be pretty much as close as conceivable to the genuine natural case [3]. AERMOD is the most utilized programming to numerically model air poisons scattering. This product utilizes an air scattering model dependent on the design of violent environmental layers and on the scaling idea, including the treatment of various point sources at ground level or at tallness. This product utilizes the Gaussian scattering model for the stable environmental conditions and non-Gaussian model for precarious barometrical conditions [4].

### 2. Environmental scattering models

The environmental scattering describes the reality development of a set of particles (vaporizers, gases, dust) produced into the environment. The environmental scattering marvel is affected by the barometrical conditions, the territory oundaries and outflow esteems. The numerical recreation of contaminations' scattering into the climate



is utilized for assessing the focus of contaminations transmitted from the mechanical action or auto traffic downwind [5].

The contributions for the air scattering models are:

- the meteorological conditions (wind speed and bearing, air choppiness, air temperature);
- the discharge boundaries (source area and stature, stack width, mass stream rate and speed, and exhaust temperature);
- the geographic information of the source and recipient;
- the area and sizes of blocked articles (structures or different constructions).

The fundamental barometrical scattering models are: Gaussian model, Eulerian model, Lagrangian model, the model of rising smoke cloud, semi-observational model, substance model, receptor model, and stochastic model [6].

### **2.1. The scattering coefficients**

The standard deviation  $\sigma$  values, additionally called scattering coefficients, showing up in the conditions portraying the focus, depend on exploratory information got from the investigation of toxins development. The most utilized scattering coefficients are;

- Pasquill-Gifford coefficients, additionally called country Pasquill coefficients;

- McElroy-Pooler coefficients, likewise called metropolitan Briggs coefficients.

The standard deviations rely upon the landscape design (provincial region with open level ground, or metropolitan region with tall structures) and the air dependability (the inclination of the combination on the upward bearing due the regular flows convection) [7]. Pasquill has separated the environmental security into six classes to address the reformist increment of the air security that impact the parallel and vertical scattering. Table 1 reports the Pasquill solidness classes, as an element of sun oriented radiation impact and season of day when the climatic scattering model is considered [8].

The qualities of the soundness classes are:

- A: very unsteady, the temperature inclination  $< - 1.5^{\circ}\text{C}/100\text{ m}$ , and the tuft is unequivocally swaying depicting the circles;
- B: decently flimsy, the temperature inclination in the reach  $- 1.5 - - 1^{\circ}\text{C}/100\text{ m}$ , the crest is firmly swaying with turbulences;
- C: marginally insecure, the temperature angle in the reach  $- 1 - - 0.5^{\circ}\text{C}/100\text{ m}$ , the tuft is somewhat swaying, firmly tapered;
- D: impartial (adiabatic), the angle temperature in the reach  $- 0.5 - 0.5^{\circ}\text{C}/100\text{ m}$ , the crest is funnel shaped without convective disturbance;



- E: isothermal, the temperature angle in the reach 0.5 – 1.5 °C/100 m, the tuft is conelike without convective disturbance;
- F: reversal, the temperature angle > 1.5 °C/100 m, the tuft has the banner structure with bringing down propensity [Error! Bookmark not defined.].

[m],  $\sigma_z$  – standard deviation of the vertical distribution emission [m],  $\sigma_y$  – standard deviation of the horizontal distribution emission [m].

Estimation of Pasquill Stability Classes <sup>*</sup>					
Surface (10m) Windspeed (m/s)	Daytime			Nighttime	
	Incoming solar radiation <sup>**</sup>			Cloud cover fraction	
	High	Moderate	Low	≥4/8	≤3/8
<2	A	A-B	B	.	.
2-3	A-B	B	C	E	F
3-5	B	B-C	C	D	D
5-6	C	C	D	D	D
>6	D	D	D	D	D

<sup>\*</sup>A-extremely unstable, B-moderately unstable, C-slight unstable, D-neutral, E-slight stable, F-moderately stable. <sup>\*\*</sup>Solar radiation: high (> 700 W/m<sup>2</sup>), moderate (350-700 W/m<sup>2</sup>), low (<300 W/m<sup>2</sup>).

### 3. Air pollutants dispersion

#### 3.1. The pollutant concentration

The general Gauss dispersion equation, for a continuous point source of pollutants as a cloud of smoke resulting from the chimney of evacuated pollutants in the atmosphere, is calculated with [9]:

$$C(x, y, z) = \frac{Q}{u\sigma_z\sqrt{2\pi}} e^{-\frac{y^2}{2\sigma_y^2}} \left[ e^{-\frac{(H_r - H_e)^2}{2\sigma_z^2}} + e^{-\frac{(H_r + H_e)^2}{2\sigma_z^2}} \right]$$

where, as shown in Fig. 1,  $C$  is the emission concentration [g/m<sup>3</sup>],  $Q$  – emission source rate [g/s],  $u$  – horizontal wind velocity,  $y$  – lateral distance from the plume center,  $H_e$  – the effective plume height above the ground [m],  $H_r$  – receiver height

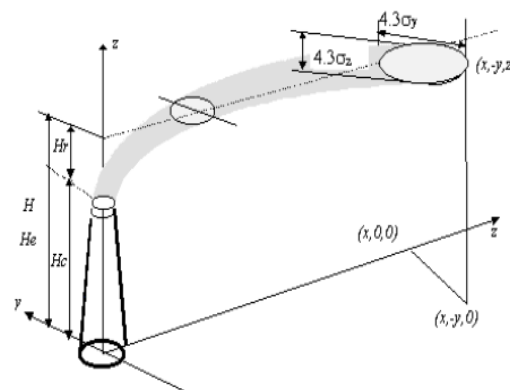


Fig. 1. Gaussian coordinates system for horizontal and vertical dispersion

The two sets of dispersion coefficients are illustrated in Fig. 2 (a), for the horizontal direction, respectively Fig. 2 (b) for the vertical direction.

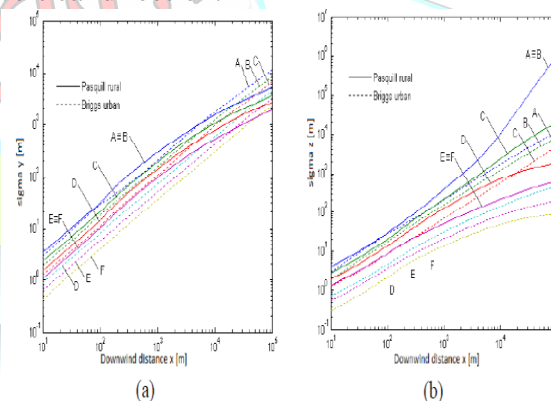


Fig. 2. Dispersion coefficients: (a) horizontal direction, and (b) vertical direction

While the Gaussian conditions have been generally utilized for air dissemination computations, the absence of capacity to remember changes for wind speed with



stature and nonlinear synthetic responses restricts the circumstances where they might be utilized. The air dissemination condition gives a more broad way to deal with air dissemination computations than do the Gaussian models. The Gaussian models have been demonstrated to be extraordinary instances of that condition when the breeze speed is uniform and the vortex diffusivities are steady. rticulation (2) is the air dissemination condition without compound response [10]:

$$\frac{\partial c}{\partial t} + \bar{u} \frac{\partial c}{\partial x} + \bar{v} \frac{\partial c}{\partial y} + \bar{w} \frac{\partial c}{\partial z} = \frac{\partial}{\partial x} \left( K_{xx} \frac{\partial c}{\partial x} \right) + \frac{\partial}{\partial y} \left( K_{yy} \frac{\partial c}{\partial y} \right) + \frac{\partial}{\partial z} \left( K_{zz} \frac{\partial c}{\partial z} \right) \quad (2)$$

where  $u$ ,  $v$ ,  $w$  are the functional forms of wind velocity, and  $K_{xx}$ ,  $K_{yy}$ ,  $K_{zz}$  are the eddy diffusivities.

The expressions available for  $K_{zz}$  are based on the Monin – Obukhov similarity theory, coupled with observational or computationally generated data, [11]. These expressions can be organized according to the type of stability.

### 3.2. The lifting height of the smoke plume

To compute the contamination fixation, the range from which the scattering is beginning must to be known. On account of the capability of simple calculation, Briggs, [12] is the favored strategy. This strategy represents the ascent of tuft capacity of downwind distance, the crest convey limit, and wind speed [7, 12]. The estimation calculation is:

- Calculating the ascending  $F$

$$F = \frac{g}{4} \pi w_{e,c} D_{i,c}^2 \frac{T_{e,c} - T_a}{T_{e,a}} = g V_{e,c} \frac{T_{e,c} - T_{e,a}}{T_a} = \frac{g Q_{e,c}}{c_{p,a} \rho T_a} \quad (3)$$

where  $F$  is the ascending flow;  $g = 9.80665$  [m/s<sup>2</sup>], the gravitational acceleration;  $w_{e,c}$  the exhaust gas velocity from chimney [m/s];  $D_{i,c}$  the inner diameter of chimney [m];  $T_{e,c}$  the absolute temperature of the gas to exit from chimney [K];  $T_a$  the absolute air temperature on top [K];  $V_{e,c}$  the volumetric flow of the exhaust gases [m<sup>3</sup>/s];  $Q_{e,c}$  thermal flow emitted by chimney [kJ/s];  $c_{p,a}$  the air specific heat at constant pressure [kJ/kgK];  $\rho_a$  air density [kg/m<sup>3</sup>]. - Calculating the downwind distance  $x_f$  where the plume height is maximum

$$x_f = \begin{cases} 49 \cdot F^{5/8}, & \text{for } F < 55 \\ 119 \cdot F^{2/5}, & \text{for } F \geq 55 \end{cases} \quad (\text{for stability classes A, B, C, D}) \quad (4)$$

$$x_f = 3.14 \frac{u}{s^{0.5}} \quad (\text{for stability classes E, F}) \quad (5)$$

## 4. Mathematical modeling

### 4.1. Software description

The product bundle FlexPDE was utilized for the numerical demonstrating of air contamination scattering. This limited component model developer and athematical solver carries out the numerical model and presents the graphical yield of the results. FlexPDE is additionally a critical thinking climate, playing out the whole scope of capacities important to tackle fractional differential condition framework: an proofreader for planning scripts, a lattice generator for building limited component networks, a limited component solver to discover arrangements, and a designs framework to plot results. The prearranging language permits the client to portray the math of his fractional differential conditions





framework and the math of his concern space [13].

#### 4.2. 2D air poisons scattering demonstrating

Utilizing the conditions and the coefficients of the air scattering, various portrayals of the poisons fixation capacity of surface and shape can be gotten. For the numerical demonstrating of poisons (SO<sub>x</sub>, NO<sub>x</sub>, PM 10) from a point wellspring of contamination, for example the exhaust smokestack of the fuel gasses, the following data sources are required:

- the components of the demonstrating space;
- wind speed (u);
- the toxin stream (Q) ;
- the chimney stack (H);
- soundness class (A-F);
- the landscape type (rustic or metropolitan).

For the numerical demonstrating, the accompanying data sources were utilized  $\mu=6$  m/s,  $Q=200$  g/sC= 20 g/m<sup>3</sup>, H = 50 m, soundness class A, country landscape, the space measurement 500x200 m.

Two models were executed, for various time-frames like  $t = 50$  s what's more,  $t = 100$  s. Fig. 3 delineates the contamination focus profile in the reenactment space for the double cross time frames. As displayed, the contamination advancement increments with the development of calculation time. To achieve a toxin scattering displaying on a more

extensive field, a higher calculation time is suggested, in any case, prompting a more drawn out reaction time.

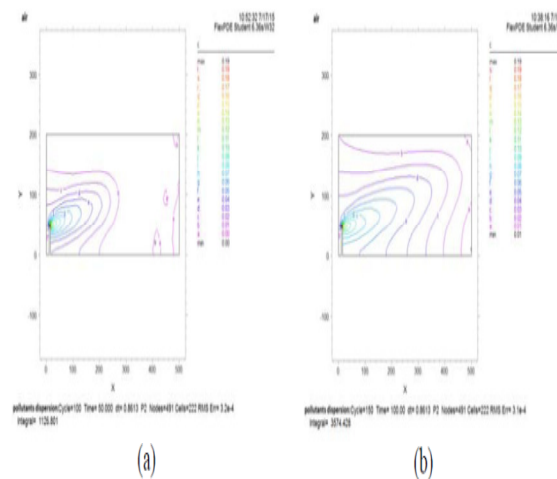


Fig. 3. The pollutant concentration profile in the simulation domain (a) s, (b)

Fig. 4 shows the evolution of pollutant's concentration for the two timeperiods. Fig. 5 shows a zoom image of the results obtained in Fig. 4.

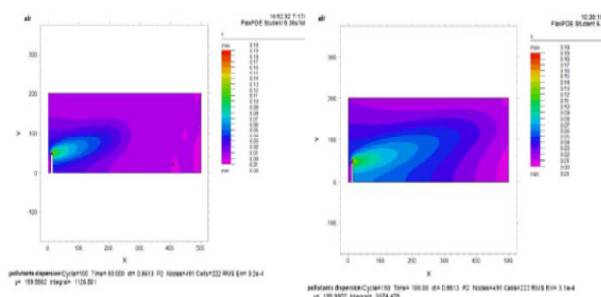


Fig. 4. The concentration evolution in time (a) s, (b) s

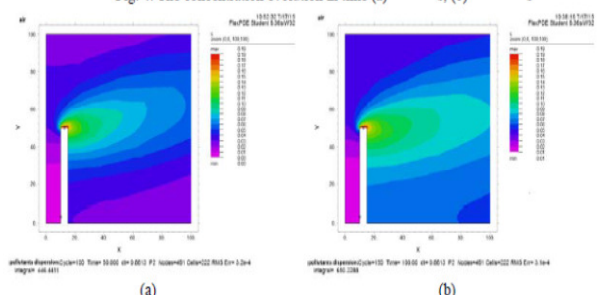


Fig. 5. Zoom on the concentration evolution in time (a) s, (b) s

The considered pollutant is the mixture composed of SO<sub>x</sub>, NO<sub>x</sub> and PM<sub>10</sub> with a total concentration  $C = 0.19$  g/m<sup>3</sup>.

## 5. Conclusions

Because of the air scattering measure, the toxin focus may change in each place of the space. In view of the directed examination, the blunders fluctuate opposite relatively with the processing time. The information sources information should go along, as precisely as could really be expected, with the meteorological conditions, geographic area, and the contamination outflows source boundaries. The breeze speed is vital inside the numerical model for depicting the advancement of the crest as near the truth. The outcomes of the mathematical reproduction utilizing the FlexPDE programming shows the scattering of contamination's focus. The outcomes affirm the hypothetical examinations as the variety of discharge's fixation stays consistent with

the alteration of stature. Be that as it may, the grouping of emanation (the dirt statement) is adjusting in space with the stature. This numerical model can be a helpful instrument in assessing air contamination from the modern regions.

## REFERENCES

- [1] J. H. Seinfeld, S. N. Pandis, Atmospheric chemistry and physics from air pollution climate change, California Institute of Technology, University of Patras and Carnegie Mellon University, John & Sons Inc., Hoboken, New Jersey, 2006.
- [2] G. T. Csanady, D. Reidel, Turbulent Diffusion in the Environment, Dordrecht, Holland 1973.
- [3] L. C. Andrei, Dispersia poluantilor in cursurile naturale (Pollutants dispersion in natural courses), National Institute of Hydrology and Water Management, 2011.
- [4] V. Busini, L. Capelli, S. Sironi, G. Nano, A. N. Rossi, S. Bonati, Comparison of CALPUFF and AERMOD Models for Odour Dispersion Simulation, Chemical Engineering Transactions, 2012.
- [5] M. C. Tita, Craiova University, Modelarea dispersiei atmosferice a poluantilor (Atmospheric dispersion modeling of the pollutants), AGIR 2012.
- [6] N. Moussiopoulos, E. Berge, T. Bøhler, K. Grønskei, S. Mylona, M. Tombrou, Ambient air quality pollutant dispersion and transport models, European Environment Agency, January 1996.
- [7] G. Lazaroiu, Impactul CTE asupra mediului (Impact of power plant on the environment), Politehnica Press, 2005.
- [8] S. Ivanov, Modelare și simulare—sisteme electromecanice, procese de mediu (Modeling and simulation—electromechanical systems, environmental processes), Editura



Universitaria, Craiova, 2007, ISBN 978-973  
742-626-0.

[9] *M. Beychok*, Fundamentals of stack gas dispersion, 2005, ISBN 0-9644588-0-2.

[10] *R. G. Lamb, and D. R. Duran*, (1977) Eddy diffusivities derived from a numerical model of the convective boundary layer, *NuovoCimento*1C, 1-17.

[11] *M. Pahlow, M. B. Parlange, F. Porte-Agel*, On Monin-Obukhov similarity in the stable atmospheric boundary layer, Department of Geography and Environmental Engineering, Kluwer Academic Publishers, 2001.

[12] *J. G. Lazaroiu*, Dispersia particulelor poluante (Pollutant Particles Dispersion), Editura AGIR 2006.

[13] FlexPDE, User Guide, 2000

