



Sparse Representation based Classification on Automatic Target Recognition

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Abstract- This paper introduces a sparse representation based classification on automatic target recognition in Synthetic Aperture Radar (SAR) image. Here, it exploits an analytic signals of real valued function generalize to capture the characteristics of SAR image. The multiple components of the monogenic signal are applied into recently developed framework, sparse representation- based classification (SRC). The nonliteral operating conditions such as structural modifications, random noise corruption, and variations in depression angle, are performed with various baseline algorithms. It also includes the working function of linear support vector machine, SRC and sparse representation of monogenic signal. The Moving and Stationary Target Acquisition and Recognition database will demonstrate under standard operating condition and robust towards noise corruption and depression variations.

Index terms- The monogenic signal, monogenic scale space, spare representation based classification.

1. INTRODUCTION

Synthetic Aperture Radar (SAR) has been used in many fields with high resolution optimal imaging sensors. SAR provides a capability of monitoring the environmental, earth resource mapping and military surveillance system that requires broad area imaging at high resolution. This imaging technique will also acquires during inclement weather conditions. The main function of automatic target recognition (ATR) is to detect and recognize the object in image by synthetic aperture radar. The signal processing uses automatic target recognition techniques to find out the unknown targets. So, one-foot resolution of the radar will easily discriminate small and large vehicles from the surrounding. SAR ATR will define a distance metric condition between the query and templates generated by various aspect view image of the object. The decision is made to find out the target to which the template belongs.

SAR has three separate stages detection, discrimination and classification. The detection focuses on

finding the local Regions of Interest (ROI) which include targets and numerous false alarms. The discrimination is used to filter the natural clutter out, for the identities of targets. The SAR images contain coherent speckle noise, which lowers the image quality significantly, so it is very difficult to interpret them from multiple distributed targets. Here sparse representation is used to search for the most compact representation of signal in terms of linear combination, using multi scale and multi orientation. The sparse representation is generated by evaluating the class of samples, which could recover the query as accurate as possible. The training set generates a methodology which usually defines distance between the test sample and the templates. The correlation pattern recognition has been presented to improve the performance of training set. The nonlinear classifier is used for the SAR ATR for the better performance in conventional template based approaches. A set of classifier is to be trained by the training samples in order to reduce their complexity, over a given range of aspect angles. Thus the performance of an algorithm is limited by the accuracy of the aspect angle estimate.

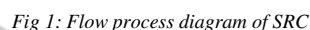
Sparse Representation based Classification (SRC) are recommended to the framework which is extensively utilized in many classification. The framework is re-explained from the perspective of class manifolds in the classification on MSTAR targets. The SRC focuses on extracting effective features to improve the classification performance. The main advantages of monogenic wavelet transform offer a geometric representation for gray scale image. The monogenic binary coding is presented for biometric recognition in which the components of the monogenic signals are encoded by various binary pattern schemes. The score level fusion at various scales used to generate three different feature descriptions, from which three sparse representations based classification, can be built. The fusion method can improve the target classes which is not effective and not linearly separable. MSTAR images have high dimensionality and speckle noise thus makes the classification more complicated and influencing



2. RELATED WORK

2.1 Sparse Representation based Classification

The SAR images of the same target taken at different aspect angles show great differences, which precludes the existence of a rotation invariant transform. This results from the fact that a SAR image reflects the fine target structure at a certain pose. The database used for training is same set of images and their performance is evaluated under identical testing condition in terms of confusion matrices.



2.2 Support Vector Machine

Support Vector Machine (SVM) are a new statistical learning technique that can be used for training classifier based on polynomial function, radial basis function, neural network. It uses a hyper linear separating plane to create a classifier. This vector machine provides a possibility to find a solution by making a nonlinear transformation of the original input space into a high dimensional feature space, where an optimal separating hyper plane can be found. Three strategies of learning and representation builds support vector machine, quadratic mutual information cost function for neural networks, and a principal component analysis extended with multi-resolution.

3. EXISTING SYSTEM

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strategy which define a distance metric to quantify the similarity between the query and templates generated by various aspect view images of the objects. The decision is made by evaluating which class of samples could recover the query as accurately as possible. Since SAR images of a given class lie in a manifold, whose dimension is much lower than the actual one, the training images can be assumed to be the samples drawn from the manifold. Then, the classification of SAR image is equivalent to finding the manifold that is closest to the query image. According to the point of local linear embedding algorithm, linear representation can be provided to any nonlinear manifold if only a small local region is considered. Thus, it is applicable for sparse signal representation to SAR image-based target recognition the mutability of the scattering phenomenology. In addition, the computational cost is unattractive because of the repetitious convolution with the templates. It relies on representing the intensity of SAR image with a parameterized statistical distribution model. It has been built around the Riesz transform, a 2D vector-valued extension of Hilbert transform.

3.1.1 Drawbacks

- Template matching method usually suffers the presence of coherent fading as well as a misalignment.
- A family of methods named correlation pattern recognition have been presented
- The matching procedure will be in the frequency domain.

4. PERFORMANCE DESCRIPTION

4.1 Data Acquisition

Synthetic aperture radar is a form of radar in which multiple radar images are processed to yield higher resolution images that would be possible by conventional methods. SAR system employs a linear antenna mounted on a moving platform which is used to illuminate the target area. The SAR ATR is performed using the MSTAR database to classify the targets.

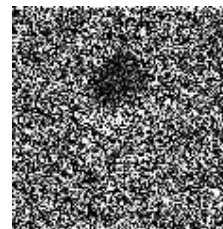
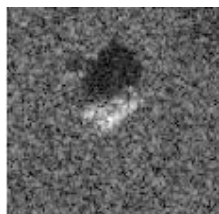


Fig 2: a) input image b) Binarization of the image

Here the SAR image which is generated upload the maximum number of images to database represented as monogenic signal. The input of a query image is taken from image database captured by the various view of the object.

4.2 Data pre-processing

In order to standardize the information each images is classified by the depression of target. SAR images taken at different aspect views show a great difference of scattering phenomenology. The pre-processing steps improve the result to get better threshold value, accuracy over multiple components simultaneously. It also unifies the sizes of the images, reduces the complexity and improves the performance of the classifiers.

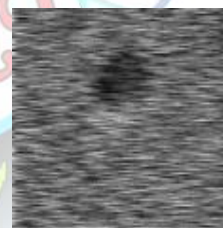


Fig3: Image before filtering

4.3 Filtering

Median filtering is to replace each pixel value in an image but the median of its neighbourhood. The median filter is normally used to reduce noise in an image usually like the mean filter. It performs much better than standard averaging FIR filter which tend to significant portion of signal high frequency content along with noise. Here the speckle noise in SAR is generally serious, causing difficulties for image interpretation.

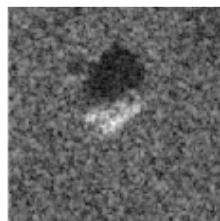


Fig 4: Image after filtering

So median filter is used to remove the noise which is severely corrupted by the defectives i.e. the locations are randomly decided. The median filter considers each pixel in the image to decide whether it is representative of its surrounding. The median filter is performed by sorting all the pixel value from the surrounding neighbourhood into numerical order and replaces the pixel with middle pixel value. The median filter has the tendency of removing noise from corrupted images. It also decompose the query image in Savitzky-galay filter that can applied to a set of digital data point for the purpose of smoothing data, that is to increase the signal to noise ratio without greatly distorting the signal. So the filtering method reduces the noise in corrupted images.

5. EXPERIMENTS AND DISCUSSION

The MSTAR database has SAR target which are collected at two different depression angles (15° and 17°). The classifier using this database is to be trained using target at the 17° depression angles and tested on target at the 15° depression angles. The overall recognition rate is obtained using various methods. The truth target with multi variant standardise the training set while the remaining are used for testing, from which the EOC different on depression and configuration are simultaneously evaluated. This result that tolerant towards variation in configuration and depression could be improved by monogenic signal representation. The one foot resolution of the image allows the radar to discriminate from the surrounding areas.

5.1 Verification of Target

The SAR image are cropped around 128×128 pixel to 80×80 pixel size utilized to principal component analysis. The three different target TG1, TG2, TG3 are utilized, from which one is taken at 17° depression while the remaining are collected at 15° depression are used for testing i.e. the variant used for testing are not contained in the training set.

5.1.1 Comparison with the Conventional Method

The proposed method has baseline algorithm which is used to assess the accuracy of individual class as well as confusion matrices. The recognition rates are obtained by different conventional method SRC, MSRC, KSVM, SUM, MAP which improves the overall accuracy as well as individual recognition rate in baseline methods. This is because both configuration and depression are significantly different between the image used for training and those used for testing the target. The classifications via score level fusion and kernel achieve significant improvement in overall accuracy. The monogenic signal representation is capable to capture the broad spectral information and simultaneous spatial localization with compact support, also contributes better performance. Thus the similarities between a pair of samples can be measured in a sufficiently feature space.

5.1.2. Retrieve Output Target Recognition.

To retrieve output target recognition the corrupted pixels are randomly chosen from the image levels the noise corruption. The robust version of SRC, which solves the extended norm minimization deals with the occlusion the performance are degraded with the range of corruption increased. The target are much more robust towards the EOC difference on depression than the other base line methods. Images taken at 17° depressions are used to train the algorithm, while the other captured at 15° , 30° , and 45° are used for testing. The overall recognition rate is obtained by confusion matrices using various methods. It adheres to standard set fort to trained the algorithm at an operating condition at 17° depression and test them at an operating condition of 15° depression i.e. a change of 2° from 17° to 15° exceeds between the image used for training and those for testing.

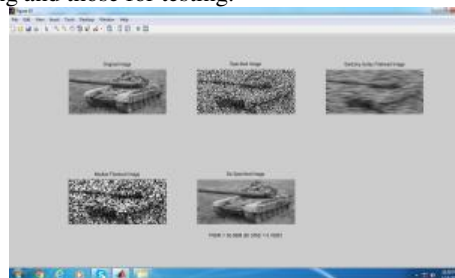


Fig 5: Filtering and De-speckled output image

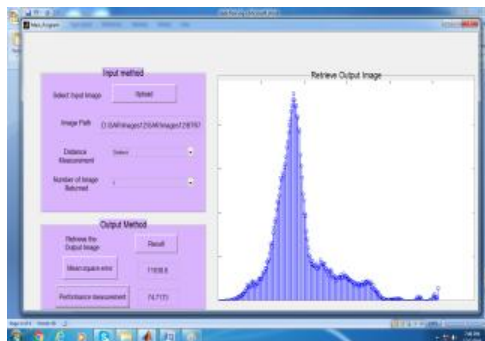


Fig 6: Simulation Result

These two targets with multi-variant are standard to get better accuracy level. To observe the performance of individual target the recognition rate with respect to each target class are performed with corresponding confusion matrices. Most of the target could be corruptly recognized with the depression and configuration of the baseline method. The output target recognition could improve the accuracy, threshold value especially under extended operating condition. Thus it improves the performance by combining multiple components simultaneously. Thus the PSNR and MSE has been calculated for each target, the high value of MSE shows the better threshold to the image.

6. CONCLUSION

The unifying framework derived from multiple components of the monogenic signal at different scales could improve the recognition accuracy and threshold. It will evaluate the class of samples that could recover the query as accurately as possible. It is robust towards EOC difference on depression and configuration, as well as noise corruption. MSTAR data set include target recognition under extended operating condition towards noise corruption as well as configuration and depression variation. So the geometric analysis is done without considering the color information and it would be much more attractive to have a complete representation of the monogenic signal into magnitude and phase with color/geometric interpretation. The MSTAR database unifies the sizes of the image, which reduces the complexity and improves the performances of classifier for improving the robustness of SRC.

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