



## **OPTIMAL HOLE COVERAGE USING IMPROVED HOLE DETECTION AND HEALING ALGORITHM IN WIRELESS SENSOR NETWORKS**

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### **Abstract**

In wireless sensor network, random deployment of nodes may cause serious coverage overlapping and the death of the nodes may also cause severe coverage problems in original network. There are several hole repair algorithms which take density of the nodes in the post deployment scenario. These algorithms consider limited mobility of the nodes and nodes with higher degree of coverage overlapping is selected. Coverage holes of the network are repaired by moving nodes which has high degree of density. This maintains uniform network density without increasing the coverage degree of the neighbor node. In existing system small holes are not considered. It only concentrates on larger holes. In the proposed work both small and large holes are considered. These holes are identified by beacon signals and are completely replaced. Here the hole detection and healing are based on two distinct phases 1)hole identification 2)hole discovery and border detection. Distributed and localized hole detection and healing algorithm deals with the holes of various forms and sizes despite node distribution and density. The proposed algorithm consumes less

amount of energy when compared to existing algorithm.

**Keywords:** WSN, Coverage overlapping, Hole detection, Hole repair algorithm

### **I. INTRODUCTION**

Wireless sensor node is a collection of nodes spread in area of interest. Wireless sensor network provides wider range of applications like monitoring battle field, environmental surveillance. Sensor deployment may be random or deterministic. Sensor nodes are mostly deployed in random manner that is, the coverage of sensor node is not uniform. There may be disconnected areas and some areas may be densely covered while some may be sparsely covered. To monitor these area maintaining the coverage and connectivity is very vital. Every point inside the region must be covered by at least one sensor node. Coverage can be classified into three classes: Area coverage, point coverage and barrier coverage. Area coverage is on how to cover an area with the sensors, while point coverage deals with coverage for a set of points of interest.



Reducing the probability of undetected penetration is the main issue in barrier coverage [17]. Coverage overlapping may be caused due to random deployment of sensor nodes. Connectivity is failed when the information passed did not reach the node.

**Types of holes:****Coverage Holes:**The holes coverage is formed when the design of the network fails. They are formed when the sensor nodes are arranged in unsystematic manner. Coverage hole can appear into existence due to poor installment, or nodes whose power consumption is weak. So they are formed by the power depletion, topology failure and by presence of obstacles.

**Routing Holes:**The routing holes that are formed when one of the node is damaged and it disables that route. Then the new route is reconstructed to outcome from the routing holes. It is caused by the power depletion and environmental disasters.

**Jamming Holes:**The jamming holes are formed when there occur any high frequency signal enters in contact with the wireless network and network breaks the incoming signal and connects with the occurrence of new signal. They are also formed when the jammers are installed in the nearby network. They are caused by the presence of obstacles.

**Black Holes:**The black holes are formed when the data's that sent by one node is not received by other node and the sender is not aware whether the data is received or not by the receiver. The data is discarded in between the traffic only. Out of all the types of holes, coverage holes are the most important to detect as they play a vital role in assuring good QoS. They help to identify whether each point in sensing field has the required degree of coverage or not. They are

the indicators of general health and help in identifying geographic characteristics of target region. Hole boundaries are used to determine the areas of interest like fire, flood, or earthquake. They help to find out locations where large number of nodes needs to be deployed and thus assist in patching the holes. Hole detection ensures reliability by preventing data loss as discussed in [18].

To guarantee complete coverage in random deployment, it is often considered that the number of scattered sensors is more than that required critical sensor density. However, this normally requires a great number of deployments of sensor nodes. The way to improve network coverage is to leverage mobile sensor nodes. Mobile sensor nodes are considered with locomotive platforms and can move around after initial deployment [16]. Voronoi diagram and Delaunay are commonly used in Wireless Sensor Network coverage optimization algorithm.

Nodes also die due to software bugs, loss of energy and destructive agents. Death of the node is considered as hole. Death of the nodes leads to packet loss. Sensory information may be lost due to node failure. To pass the data without any obstacles the node failure has to be repaired without affecting the coverage and connectivity. To recover from failure the coverage area of the node is considered. When a node is failed, the boundary of the node is detected and the neighboring nodes with maximum coverage are identified. Such nodes are moved to the region of failed nodes. By moving such nodes the existing coverage and connectivity is not disturbed.

There are several hole coverage algorithms. These algorithms consider only



multiple node failure as a hole and single node failure is not considered. These results in data loss and energy consumption of energy by the nodes are also high. Proposed hole detection and healing algorithm detects single node failure and heals it hence data loss is prevented.

Main contribution of the work is as follows:

- Connectivity is preserved by moving the neighboring nodes with high degree of density.
- Single node failure is detected and healed so that the sensory information cannot be lost.
- Coverage holes are repaired using few mobile nodes.
- The boundary range of each node is known.

## **II.RELATED WORKS**

In [1] Ammari H.M. And Das S.K. addressed the problem of k-coverage in WSNs such that in each scheduling round, every location in a monitored field was covered by at least k active sensors while all active sensors are being connected. Sensing coverage was an essential functionality of WSNs. It is also well known that coverage alone in WSNs is not sufficient, and hence network connectivity should also be considered for the correct operation of WSNs. Sensors duty-cycling strategies for generating k-coverage configurations in WSNs is studied. First, the k-coverage problem in WSNs is modeled. Second, a sufficient condition of the sensor spatial density for complete k-coverage of a field was derived. Relationship between the communication and sensing ranges of sensors to maintain both k-coverage of a field and connectivity among all active

sensors is provided. Third, four configuration protocols was proposed to solve the problem of k-coverage in WSNs. It selects a minimum number of sensors to achieve full k-coverage of a field while guaranteeing connectivity between them.

In [2] Bai.X, Yun.Z, Xuan.D. and Lai T.H. (2010) discussed about optimal deployment in terms of the number of sensors required to achieve four-connectivity and full coverage under different ratios of sensors' communication range to their sensing range .A new pattern, the Diamond pattern, which can be viewed as a series of evolving patterns was proposed. When the Diamond pattern coincides with the well-known triangle lattice pattern it degenerates to a Square pattern. The proposed pattern was asymptotically optimal when communication range achieves four-connectivity and full coverage. Another new deployment pattern called the Double-strip pattern was discovered. An asymptotically optimal deployment pattern was proposed to achieve four-connectivity and full coverage for WSNs.

In [3] Gupta.H, Zhou.Z, Das S.R.andGu.Q. (2006) designed and analyzed algorithms for self-organization of a sensor network to reduce energy consumption. Spatial query execution was an essential functionality of a sensor network, where a query gathers sensor data within a specific geographic region. Redundancy within a sensor network can be exploited to reduce the communication cost incurred in execution of such queries. One approach to reduce the communication cost of a query is to self-organize the network, in response to a query, into a topology that involves only a small subset of the sensors sufficient to





process the query. The query is then executed using only the sensors in the constructed topology. The self-organization technique is beneficial for queries that run sufficiently long to amortize the communication cost incurred in self-organization. In particular, the notion of a connected sensor cover was developed and designed a centralized approximation algorithm that constructs a topology involving a near-optimal connected sensor cover. A distributed self-organization version of the approximation algorithm is developed.

In [4] Ma .C, He.J,Chen H.H . andTang.Z. (2013) investigated the problems of hidden devices in coverage overlapped IEEE 802.15.4 WSNs, which was likely to arise when multiple 802.15.4 WSNs are deployed closely and independently. A typical scenario of two 802.15.4 WSNs with partial coverage overlapping is considered and Markov-chain based analytical model to reveal the performance degradation due to the hidden devices from the coverage overlapping is proposed. Impacts of the hidden devices and network sleeping modes on saturated throughput and energy consumption are modeled.

In [5] Mahboubi.H, Habibi.J, Aghdam A.G. and Sayrafian-Pour.K. proposed efficient deployment strategies for a mobile sensor network, where the coverage priority of different points in the field was specified by a given function. The multiplicatively weighted Voronoi diagram is utilized to find the coverage holes of the network for the case where the sensing ranges of different sensors are not the same. Under the proposed strategies, each sensor detects coverage holes within its MW-Voronoi region, and then moves in a proper direction

to reduce their size. Since the coverage priority of the field was not uniform, the target location of each sensor was determined based on the weights of the vertices or the points inside the corresponding MW-Voronoi region.

In [6] Megerian.S, Koushanfar.F, Potkonjak.M. and Srivastava M.B. addressed one of the fundamental problems, namely, coverage. Sensor coverage is the coverage that can be provided by particular sensor network. Sensor networks also pose a number of new conceptual and optimization problems. The definition of the coverage problem from several points of view was discussed and defined the worst and bestcase coverage in network. By combining computational geometry and graph theoretic techniques, specifically the Voronoi diagram and graph search algorithm, an optimal polynomial time worst and average case algorithm for coverage calculation for homogeneous isotropic sensors was established.

### **III. IMPROVED HOLE DETECTION AND HEALING FOR OPTIMAL COVERAGE**

A network of sensor nodes can be installed in different areas to monitor the events. The nodes have sensors to measure environmental conditions. The big problem in WSN is the occurrence of Holes, it was occurred by irregular manner of sensor deployment or depletion of battery.

Improved Hole detection and healing algorithm is developed. Using this algorithm holes are detected and healed. Singlenode failure is also detected as a hole. To minimize the coverage overlapping and to maximize the coverage area, an efficient holehealing algorithm is proposed by



maintaining both the connectivity and coverage of the nodes.

In such a random deployment scenario, the density of the network can be non-uniform. Density of the nodes in the large overlapping area must be higher than the density of the nodes in the sparse region. Besides, it could be possible that coverage hole is generated due to predictable or unpredictable death of the nodes. Hence, the holes are repaired by moving few sensors from the large overlapping area to the hole region so that uniform density of the nodes can be maintained in the whole network. Advantages of Proposed System include Very low complexity, increases network lifetime.

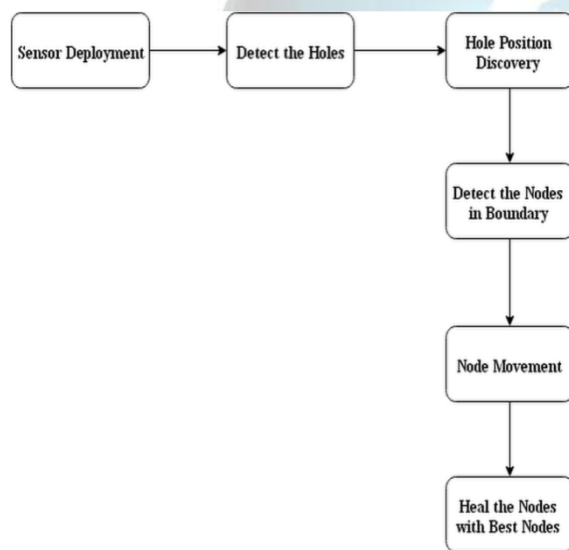


Fig 1. System Architecture

Fig 1 shows system architecture. The fundamental service provided by a Wireless Sensor Network is the monitoring of a specified RoI. The main duty of RoI is sensing the environment and communicating the available information to the sink. However, the occurrence of holes is unavoidable due to the inner nature of

Wireless Sensor Network, random deployment, environmental factors, and external attacks. Thus, its primary task is to provide self-organizing mechanism to detect and recover holes. Nodes send beacon signal from this signal the hole occurrence is identified. Then hole is discovered. The hole is temporarily healed by moving sensor nodes. Nodes are moved to the place where hole is detected and healing process is preceded. By moving nodes the packet loss is avoided.

The Hole detection and healing is done in following phases: Topology formation, Hole detection & position discovery, Border detection, Hole healing.

#### A. Topology formation

Topology formation is one of the important issue in a wireless sensor network. Wireless sensor network mainly used for monitoring the events such as disaster tactical in military surveillance. It can be placed in regular manner or irregular manner. Deploying sensors irregularly may create holes in sensor networks. Battery consumes the energy of sensors. It is considered that the sensors are randomly distributed over a large target area. Each and every sensors can sense the specified tasks in its sensing range, and communication is done with in transmission range.

#### B. Hole Detection & Discovery

DHD is the algorithm, it detects hole in WSN. Coverage holes may exist in WSNs due to presence of obstacles or invalid sensor nodes in the sensing field. The holes present makes the data routing failure. Suppose a large amount of sensor node are scattered in a geometric region,



with the nearby nodes communicating with each other directly node failure causes great data loss. Failure of node is detected using beacon signals. Nodes transfer beacon signals between them. These signals carry information like energy level, location of node. When this signal is reached to the neighbouring node the neighbouring nodes send acknowledgement back to the node. After receiving acknowledgement data will be routed. If acknowledgement is not received then the neighbouring node is considered as a failed node.

### **C. Position Discovery**

From this module the hole characteristics such as hole position and radius can be discovered. Location information of the node is attached to each node while sending beacon signals. So the position of the node from which the beacon signal is not received can be easily identified. From this the position of the hole is identified.

### **D. Border Detection**

Border detection algorithm is distributed algorithm. The boundary nodes are detected, which will launch the hole discovery and the healing process. Nodes located at the boundary of hole is identified by sending message. Node which knows the position of the hole sends message to neighbouring nodes. The node which is receiving this message calculates the distance between itself and the originator. This message is forwarded to the next neighbouring node. This node will again calculate the distance between itself and the originator and passes the message to its neighbour node. In this way the packet will reach the originator back. Now originator

will have some nodes with their distance. These nodes are considered as the boundary nodes.

### **E. Hole Healing**

Hole healing is done by moving the nearby nodes. Neighbouring nodes with high energy is selected and also the nodes are selected in such a way that its connectivity is not disturbed. Such nodes move a little from their position to recover from failure.

Nodes locomotion facilities to heal detected holes is exploited. Relocation algorithm is completely distributed. A local healing is performed only on the nodes located at an appropriate distance from the hole.

In healing process, the originator will then find the nodes with minimum distance. Christo Ananth et al. [9] discussed about a Secure system to Anonymous Blacklisting. The secure system adds a layer of accountability to any publicly known anonymizing network is proposed. Servers can blacklist misbehaving users while maintaining their privacy and this system shows that how these properties can be attained in a way that is practical, efficient, and sensitive to the needs of both users and services. This work will increase the mainstream acceptance of anonymizing networks such as Tor, which has, thus far, been completely blocked by several services because of users who abuse their anonymity. In future the Nymble system can be extended to support Subnet-based blocking. If a user can obtain multiple addresses, then nymble-based and regular IP-address blocking not supported. In such a situation subnet-based blocking is used. Other resources include email addresses, client puzzles and e-cash, can be used, which could provide more privacy. The system can



also enhanced by supporting for varying time periods.

The proposed method selects the next node to be relocated by utilizing energy in an efficient manner. By doing this, packet dropping rate decreases.

## V. RESULTS

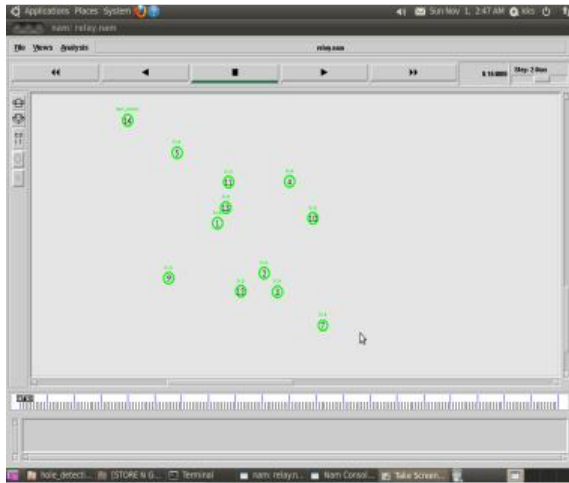


Fig 2 Node deployment

Fig 2 shows deployment of nodes. Environments like forest, battle fields nodes are deployed randomly. Random deployment means setting positions of wireless sensor nodes randomly and independently in the target area. Random deployment of nodes causes coverage overlapping. Random deployment is a feasible and practical method to deploy nodes in hostile environment.

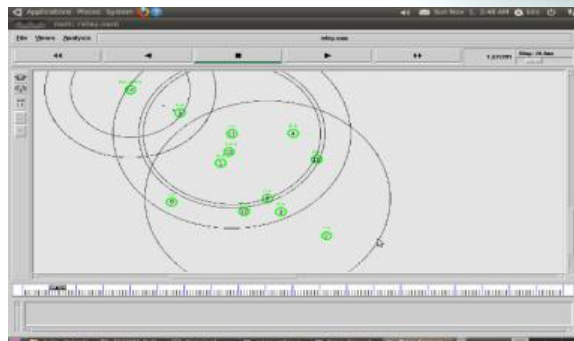


Fig 3 Data transfer between source 2 and base station 14

Fig 3 illustrates data transfer between source 2 and base station 14. Before sending data, source sends its corresponding energy level, location information to the neighbouring nodes through beacon signals. Neighbouring nodes upon receiving the signal has to send back acknowledgement to the source. Only after receiving acknowledgement data transfer takes place between nodes.



Fig 4 Failure detection

Fig 4 Node failure is detected. Failure of node is detected by beacon signals when the nodes does not send back acknowledgement. 1,11,5 indicates dead node. When the nodes are dead there is no other path for the data transfer to take place. Hence causes data loss.

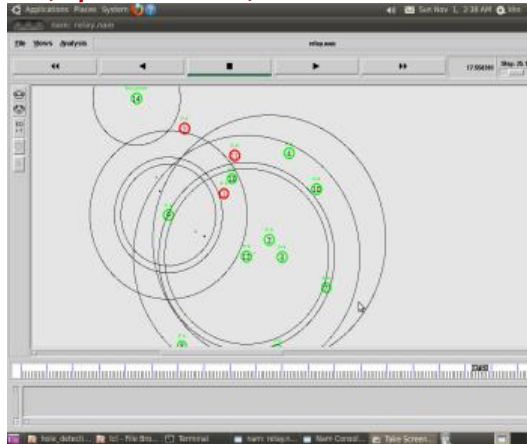


Fig 5 Hole healing

Fig 5 illustrates Hole healing. To heal the hole, neighbouring nodes are moved. Nodes are moved in such a way that its own coverage and connectivity is not disturbed. The neighbor node 9 is moved to heal the failure. After the node is passed the data transfer will be resumed through 9.

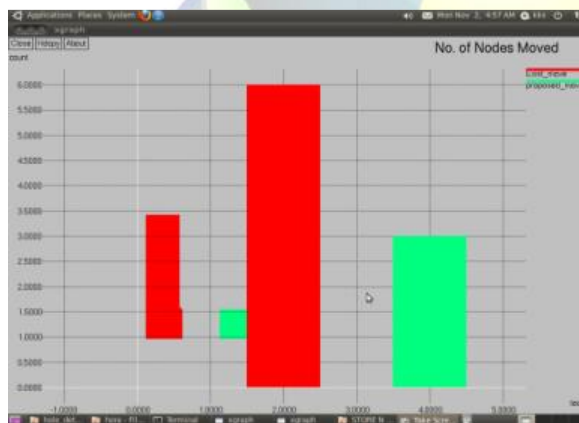


Fig 6 Comparison of number of nodes moved

Fig 6 illustrates comparison of nodes moved in existing and proposed system. Numbers of nodes are plotted along the x-axis and count is plotted along y-axis. It is clearly shown that the number of nodes moved in proposed system to heal failure is less compared to the existing system. Hence the energy consumption will be low in the

proposed system compared to the existing system

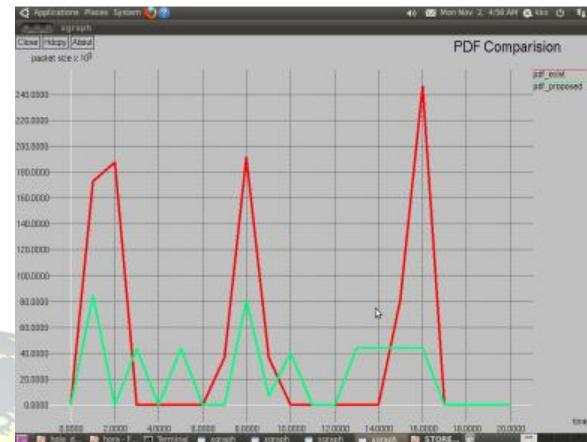


Fig 7 Comparison of packet loss

Fig 7 shows packet loss comparison between existing and proposed system. Time is plotted along x-axis and packet size is plotted along Y-axis. Packet loss is caused because of node failure. By using HHA algorithm the failure is detected and healed quickly. Hence packet loss is minimized compared to the existing system.

## V. CONCLUSION AND FUTURE WORK

Detection and healing failure is an important aspect in WSN. Hole detection and healing algorithm used increases network lifetime to make efficient network connectivity for data transmission. Failure is healed by moving neighbouring nodes from higher density area. It involves minimum relocation of nodes. So the energy consumption of the nodes is relatively low. The failure is detected and healed efficiently which reduces the packet loss.





In future work to reduce packet loss actor node is used temporarily in the place of failure. When the nodes fail the neighbouring nodes are moved to heal the failure. During the node relocation there may be packet loss until the network is formed. To reduce packet loss actor node is placed temporarily in the place of failed nodes. When the network is formed perfectly actor node will be removed and data transfer takes place between the nodes.

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