Cluster-Tree Data Collection for Wireless Sensor Networks

R.DIVYA, Mr.V.KARTHIK

[1]PG Scholar, [2]Assitant Professor, Department of ECE

[1,2] Sri Krishna College of Engineering and Technology

ABSTRACT

Wireless Sensor Networks (WSNs) are used widely in today's world. Various data collection schemes are used in WSNs. They are multipath, chain, tree, cluster and hybrid topologies. These schemes are failed to provide a guaranteed reliable network in terms of mobility, traffic and end-to-end connection. Here, a Velocity Energy-efficient and Link-aware Cluster-Tree (VELCT) scheme is used for data gathering to overcome the problems of coverage distance, mobility, delay, traffic, tree intensity and end-to-end connection. This VELCT schemes constructs the Data Collection Tree (DCT) depending on the cluster head location. The Data Collection Nodes (DCNs) in DCT does not perform sensing, it only collects the data packet from the cluster head and transmit it to the sink. This scheme reduces energy exploitation, delay and traffic in cluster head in WSNs. Simulation results shows that this scheme provides better QOS in energy consumption, throughput, delay and network lifetime.

I.INTRODUCTION

At first WSNs are used for deployment in remote and hazardous environment. It's goal is to sense the data from the sensor nodes and deliver it to the sink. Data collection is an important factor for determining the performance of WSNs. Network topology defines the types of routing path, determines the size, type of packets, dimension of the sensor node group, manages the addition of new members and withdrawal of members. When a right topology is chosen it improves the performance, coverage, lifetime and QOS of the network. An efficient topology provides the neighbors at minimum distance

and reduces the probability of the packet loss. Energy consumption is an important parameter that plays a major role in the performance of WSNs. Topologies such as flat, chain, tree, cluster and hybrid are already existed. In this paper Velocity Energy-efficient Link-aware Cluster-Tree (VELCT) scheme is proposed to overcome the existing limitations such as energy consumption, delay, traffic, coverage, connection time, RSS (Received Signal Strength), data collection, and lifetime on WSNs.

II. LITERATURE SURVEY

For data collection purpose various algorithms were used in WSNs. Some algorithms are used in cluster topology, some are used in tree topology and some are used in cluster tree topology. Low Energy Adaptive Clustering Hierarchy (LEACH) is a clustering algorithm which selects cluster head based on threshold value and received signal strength (RSS). All the sensor nodes will get a chance to act as a cluster head for a particular time. This algorithm improves the lifetime of the network and increases energy conservation as it uses single hop transmission. However it increases overhead as it causes link failure and it is not applicable for large scale WSNs. Hybrid Energy-Efficient Distributed clustering (HEED) is an energy efficient multi-hop clustering algorithm. It selects the cluster head based on the high average residual energy. This increases energy conservation and scalability. The main drawback is it uncovers several sensor nodes. Cluster head near to the sink die earlier. In Mobility Based Clustering, each sensor have a chance to elect cluster head based on threshold value. It provides better performance than LEACH, HEED and other existing protocols. But it is failed to address the critical node
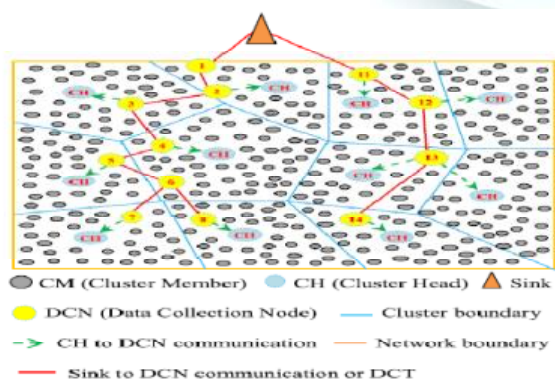
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occurrence problem which causes link breakage, packet dropping and reduces the network utilization.

Tree Based Data Collection Scheme (TBDCS) is a protocol with a collection of query messages. It uses flooding avoidance method and it sets a tree with least intermediate nodes and selects an appropriate time to aggregate the received data. It minimizes the network traffic and improves the network lifetime. However time consumption is high. Energy Efficient Data Collection Protocol Tree Based (EEDCP-TB) is a protocol which uses flooding avoidance scheme and cascading timing scheme to perform data aggregation. It minimizes energy consumption and increases network lifetime.

III VELCT DESIGN

Velocity Energy-efficient Link-aware Cluster-Tree (VELCT) is used to overcome the existing algorithms limitations such as energy consumption, coverage, RSS, throughput, connection time, end-to-end delay, and network lifetime. It is an improved version of CIDT. This scheme consist of two phase. They are set-up phase and steady-state phase. This scheme overcomes the existing problems in CIDT.

The fig1 shows the VELCT structure which helps to improve the network lifetime and executes the data gathering effectively with minimum delay. This scheme is an efficient hybrid scheme suitable for the dense wireless sensor networks. On mobility-based environments, it provides better performance.

- ⚫ CM (Cluster Member)   ⚪ CH (Cluster Head)   🔺 Sink
- 🟡 DCN (Data Collection Node)   ── Cluster boundary
- ⇢ CH to DCN communication   ── Network boundary
- ── Sink to DCN communication or DCT

A. Set-Up Phase

It consist of intra cluster communication and DCT communication operations. Here the cluster formation and data collection tree (DCT) construction is initiated to identify the correct path between the cluster members and sink. In intra cluster communication all sensor nodes selects cluster head based on threshold value and forms a cluster with better connection time, RSS, coverage time and robustness for connection. Here the sensor nodes are deployed densely over the region. Christo Ananth et al. [10] discussed about Reconstruction of Objects with VSN. By this object reconstruction with feature distribution scheme, efficient processing has to be done on the images received from nodes to reconstruct the image and respond to user query. Object matching methods form the foundation of many state- of-the-art algorithms. Therefore, this feature distribution scheme can be directly applied to several state-of- the-art matching methods with little or no adaptation. The future challenge lies in mapping state-of-the-art matching and reconstruction methods to such a distributed framework. The reconstructed scenes can be converted into a video file format to be displayed as a video, when the user submits the query. This work can be brought into real time by implementing the code on the server side/mobile phone and communicate with several nodes to collect images/objects. This work can be tested in real time with user query results.

B. Algorithm steps

(a) Declare the variables.

(b) Initialize the number of DCT to cover all the CHs over the network.

(c) Assign the value to NN and iterate the value to identify the TIN from NN.

(d) Assign the variable _ to store all CNI in TIN.

(e) Consider _ to identify the one-hop distance from NN.

(f) Check the one-hop distance NN is CH or not.

(g) Set the identity of NN as CNI.

(h) Set the NHC is one-hop distance from NN or HC.

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(i) Check the CNI is NN then NHC is one-hop distance from HC, NH is the next one-hop distance from *N* and NH is CH or not.

(j) Store CNI value into TIN array.

(k) Return null value.

(l) Check whether the value of hop count is *1* and NN is CH.

(m) Store null value in TIN[*l*+1] which uses to skip the selection of CH as CNI.

(n) Increment *i* for the next iteration to identify the next TIN.

(o) Assign TIN[0] to select the best value from TIN.

(p) Consider *j* to decrement the array length of TIN which is used to identify the DCN.

(q) Select the best value from TIN[*j*].

(r) Assign that best value to TIN[].

(s) Reassign the value of TIN to CM.

(t) Assign that best as DCN.

(u) Compute the frame duration of DCN as *t f DCN (o)*.

(v) Compare MFD and *t f DCT (_)*.

(w) Add that DCN in DCT.

(x) Now, HC is incremented from _, and it is considered to identify the one-hop distance SN from DCN _ for next DCN selection.

(y) NN is considered to one-hop distance SN from DCN _ for next DCN selection.

(z) Go to L1 for next DCT generation.

C. Steady-state phase

This phase is initiated when the set-up phase is completed. Here all the cluster members transmit the data to the cluster head in allocated time slots. Here DCT communication uses direct sequence spread spectrum (DSSS) to transfer the data from the cluster head to DCN and then the sink. DCN collects and aggregates the data from the corresponding cluster head or DCN.

IV.RESULTS

Here, various graphs are plotted for energy consumption, throughput, delay and packet delivery ratio. This is done by using the software called Network Simulator (NS-2). Here this software is used to carry out the performance study of VELCT.
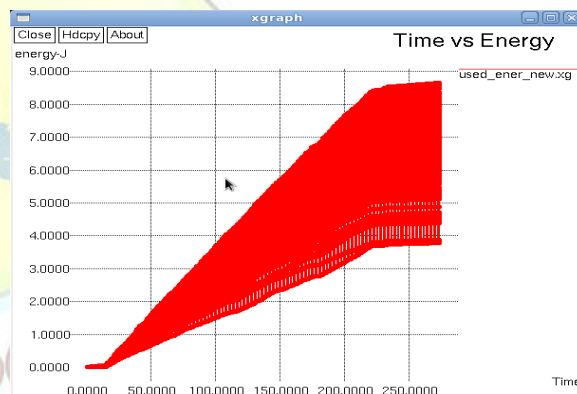

Figure 2: Time Vs Used energy

Fig 2 explains the energy used or spent for each packet during transmission at the time of every second. Thus x-axis shows time which is represented in seconds and y-axis shows energy which is represented in joules. Initially energy used or spend is very low before the packet transmission. When the packet transmission begins, the energy used or spent for the transmission increases at increase in time.

Fig 3 explains the remaining energy or the energy existed in nodes during the transmission of packets at the time of every second. Initially, i.e before transmission, the energy remains high. When the transmission begins the remaining energy

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decreases at each second. Here also x-axis shows time which is represented in seconds and y-axis shows energy which is represented in joules.
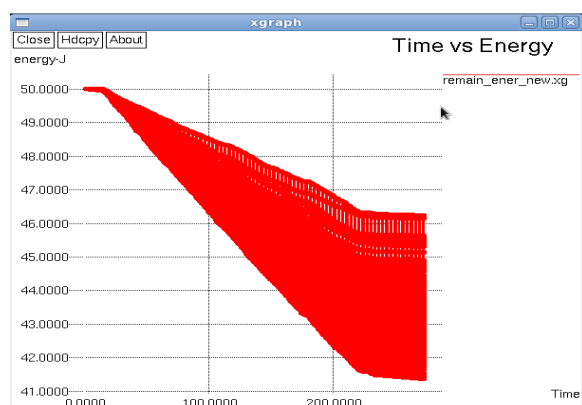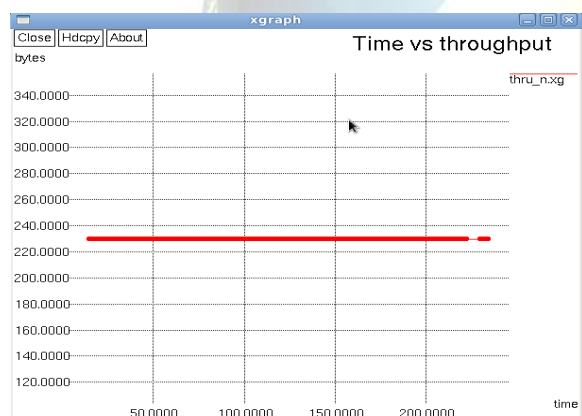

Figure 3: Time Vs Remaining energy.

Figure 4: Time Vs Throughput

Fig 4 explains the throughput for each second during transmission. Throughput is defined as the total number of bytes being received. In below graph throughput remains constant throughout the graph. So there is no packet loss. Thus the throughput of the transmission at the time of every second is approximately 230 bytes. Thus x-axis shows time which is represented in seconds and y-axis shows throughput which is represented in bytes.

Fig 5 shows the Packet Delivery Ratio (PDR), at the time of every seconds. The communication begins at 15th second. Packet Delivery Ratio is defined as the ratio of total number of packets received to total number of packets transmitted. Thus x-axis shows time which is represented in seconds and y-axis shows packet delivery ratio (PDR) which is represented in percentage. In the above graph, packet delivery ratio remains high i.e 200% at a particular time.
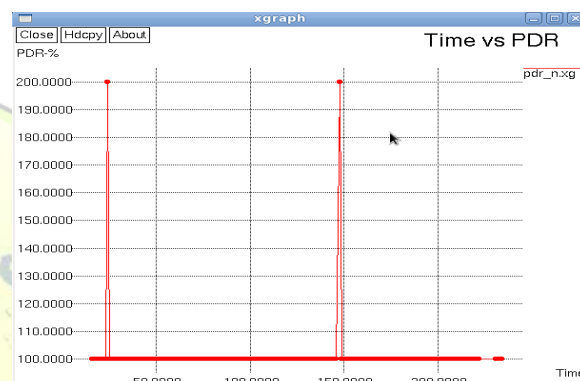

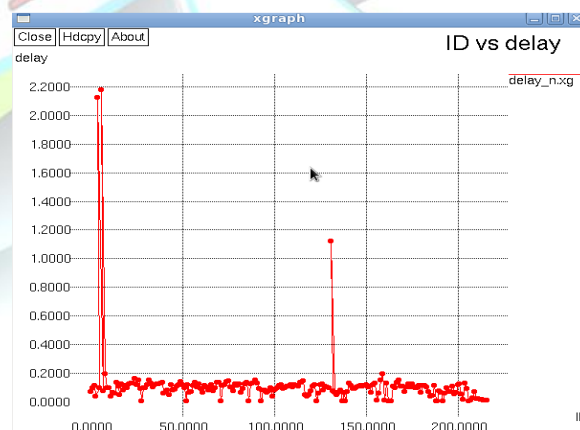Figure 5: Time Vs Packet Delivery Ratio.

Figure 6: Packet ID Vs Delay

The above graph shows the delay for the each packet identity (ID). Thus x-axis shows the ID of the each packet and y-axis shows the delay which is represented in seconds. The delay for the particular packet ID is maximum i.e 2.2 seconds. This graph

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represents the delay occurred for each packet during the transmission

V. CONCLUSION

Generally more number of sensor nodes is required to monitor the large scale areas. In this project, VELCT (Velocity Energy-efficient and Link-aware Cluster-Tree) is a proficient method to construct a network management architecture for WSNs, to improve the network lifetime, connection time, residual energy, RSSI, throughput, PDR and stable link for the sensor nodes, whereas each cluster member chooses the cluster head with better connection time and forwards the data packets to the corresponding cluster head in an allocated time slot. Similarly, the sink or DCN elects the one-hop neighbor DCN or cluster head with maximum threshold value, connection time, RSSI and with less network traffic. From the simulation results, it is revealed that VELCT provides more stable links, better throughput, energy utilization and PDR with reduced network traffic than existing protocols such as EEDCP-TB, CREEC, CTDGA, MBC and CIDT.

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